## M.E. Second Semester (Electrical & Elect.) (New-CGS) 13290: Neuro Fuzzy Control: 2 EEEME 3

P. Pages: 2
Time: Three Hours

Notes: 1. Due credit will be given to neatness and adequate dimensions.

2. Assume suitable data wherever necessary.

3. Illustrate your answer necessary with the help of neat sketches.

Illustrate your answer necessary with the help of neat sketches. SECTION - A 7 1. a) Prove that the De Morgan's law  $(\overline{A \cup B}) = \overline{A} \cap \overline{B}$  is true for fuzzy sets A and B using Zadeh's operator for union, intersection and complement. 6 b) Explain the term Linguistic variable. Differentiate between Linguistic variable and Linguistic terms. OR Compute the cylindrical extension of fuzzy set  $A = \{0.3/x_1; 0.4/x_2\}$  into the cartesian 7 2. a) product domain  $\{x_1, x_2\} \times \{y_1, y_2\}$ . 6 Explain in details "Fuzzy Partition"? b) 7 Discuss the design of an Automobile Cruise control system using fuzzy approach. 3. a) Explain design of fuzzy controller to control dynamics of a DC servo-motor also compare b) 7 with classical controller design. OR 7 Discuss motion of stability of fuzzy control system. How it is determined? 4. a) 7 Explain Takagi - Sugeno - Kang [TSK] architecture for fuzzy controller. b) 6 5. Explain back propagation learning algorithm in detail. a) 7 b) Derive the back propagation rule for output neuron with a sigmoidal activation function.  $\mathbf{OR}$ Explain why delta rule is not used for training multi layer neural network. 6 6. a) 7 b) Explain how feed forward neural network used for the control. Also assume input layer contains situational and goal variables and output layer contains

AW - 3843

Max. Marks: 80

action variables.

## SECTION - B

7 7. Develop optimal neural network model for controlling temperature. a) 7 How do you simulate a P.I. control with a neural network? b) OR Explain applications of neural network design in direct neural control. 8. a) 7  $\mathbf{A} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -5 & -2 & -3 \end{bmatrix} & \mathbf{B} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ 7 b) compute U based on inverse dynamics. 9. Explain the term ANFIS in detail. a) 6 b) Explain basic principles & applications of fuzzy neural system. 7 OR 10. Describe Hybrid neural set (network) a) 6 Illustrate: AND Fuzzy neuron i) ii) OR Fuzzy neuron b) Describe hybrid neural network hence define basic principles of fuzzy neural system. 7 11. Design a neuro fuzzy control system for Integrated Pest Management. 13 OR 12. Discuss fuzzy logic based control scheme for thermo-electric cooling of laser material. 13

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2

AW - 3843