

M.E. First Semester (Electronics & Tele.) (Full Time) (C.G.S.- New)
13337 : Elective-I : Artificial Intelligent System : 1 ENTC 5

P. Pages : 2

Time : Three Hours



AW - 3632

Max. Marks : 80

- Notes :
1. Assume suitable data wherever necessary.
 2. Illustrate your answer necessary with the help of neat sketches.
 3. Use of pen Blue/Black ink/refill only for writing the answer book.

1. a) List the various properties of fuzzy sets. Do the law of excluded middle & law of contradiction hold for fuzzy sets? Prove. 7
 b) What is defuzzification? Explain different defuzzification methods. 7

OR

2. A fuzzy relation matrix \tilde{R} is given 14

$$\tilde{R} = \begin{bmatrix} 1 & 0.8 & 0 & 0.1 & 0.2 \\ 0.8 & 1 & 0.4 & 0 & 0.9 \\ 0 & 0.4 & 1 & 0 & 0 \\ 0.1 & 0 & 0 & 1 & 0.5 \\ 0.2 & 0.9 & 0 & 0.5 & 1 \end{bmatrix}$$

Justify that \tilde{R} represents a tolerance relationship.

Reform this tolerance relation into equivalence relation.

3. a) Explain canonical forms of a fuzzy rule-based system. What do you understand by aggregation of fuzzy rules? Explain with example. 7
 b) Explain different fuzzy ranking methods with suitable examples. 6

OR

4. a) In a temperature controller for room, the Linguistic comfort range is "slightly cold" and "not too hot" using these membership functions defined on the universe of temperature in °Celsius. 7

$$\text{Hot} = \left\{ \frac{0}{25} + \frac{0.1}{26} + \frac{0.3}{27} + \frac{0.5}{28} + \frac{0.7}{29} + \frac{0.9}{30} \right\}$$

$$\text{Cold} = \left\{ \frac{0.2}{30} + \frac{0.3}{29} + \frac{0.4}{28} + \frac{0.7}{27} + \frac{0.8}{26} + \frac{1}{25} \right\}$$

Find the membership functions for

- i) Not very hot
- ii) Slightly cold or slightly hot

- b) Discuss graphical inference technique with appropriate example. 6

5. a) Summarize in point form the design steps of a fuzzy logic controller (FLC). How is turning achieved in FLC. 6
 b) A fuzzy relation matrix is given by : 7

$$M = \begin{bmatrix} 0.1 & 0.8 \\ 0.4 & 0.2 \end{bmatrix} \text{ on } x = \{1, 2\} \text{ \& } y = \{1, 2\}$$

determine whether the system is stable, oscillating or unstable.

OR

6. Design a fuzzy PI controller for a series DC motor. Assume suitable data for the variables used. 13
7. a) Consider the classification problem defined below : 6
- $$P_1 = \begin{bmatrix} -1 \\ 1 \end{bmatrix}; P_2 = \begin{bmatrix} 0 \\ 0 \end{bmatrix}; P_3 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}; P_4 = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \& P_5 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$
- Given $P_1, P_2 \& P_3$ in class I
 $P_4 \& P_5$ in class II
- Is this problem linearly separable?
 If yes draw the single neuron perceptron to solve this problem.
 If no, justify your answer.
- b) Derive an expression for a generalized delta rule for a feed forward neural network with single hidden layer. 8
- OR**
8. a) Discuss various activation functions used in neural networks. 8
- b) Differentiate between cumulative weight adjustment and incremental weight adjustment. 6
9. Design a Hopfield network for storing following 4 bit bipolar patterns. 13
- $$S_1 = [1, -1, -1, -1]$$
- $$S_2 = [-1, 1, 1, -1] \&$$
- $$S_3 = [-1, -1, -1, 1]$$
- Find energy associated with each sample. Use retrieval algorithm to determine association of the sample $[-1, 1, -1, -1]$.
- OR**
10. a) Discuss the Kohonen's self organization of feature map learning algorithm. 7
- b) Describe the architecture of BAM and discuss its training algorithm in detail. 6
11. a) Explain the following steps in Genetic Algorithm. 6
- i) Cross over ii) Mutation
 iii) Reproduction
- b) Explain how the robot manipulator with two -- degree of freedom can be controlled using Artificial Neural Network. 7
- OR**
12. a) Following two dimensional patterns for a 2 – class problem used to be classified using SVM. Determine hyperplane using suitable support vector. 6

x_1	0	0	0.5	0.75	0.75	1.0
x_2	0	0.5	0	0.75	1	0.75
Class	+1	+1	+1	-1	-1	-1

- b) Discuss various steps involved in designing a neural network for printed character recognition with suitable example. 7
